

Syllabus

5. Graph Problems

- Recap on Graphs: un/directed, weighted
- Shortest Paths: single-source, all-pairs
- Minimum Spanning Tree: Prim, Kruskal
- Maximum Flow: Ford-Fulkerson, Edmonds-Karp
- Maximum (weighted) Bipartite Matching
- Minimum Cut

5. Graph Problems

graph recap

Specification: Graph $G=(V,E)$, $n=\#V$ vertices, $m=\#E$ edges

Basic graph concepts:

- simple: no *multi*-edges nor loops
- in-/out-/degree
- (un-/directed) path
- (strongly) connected component
- subgraph, induced graph

$E \subseteq V \times V$ directed edges

E symmetric: undirected edges

$w: E \rightarrow \mathbb{N}$ edge weights $\infty/0$: absent
1: present

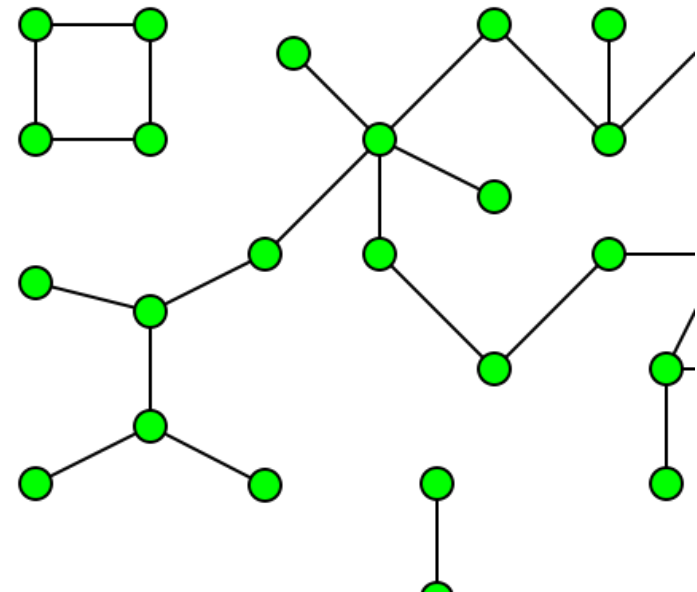
Handshaking lemma:

$$\#E = \sum_{v \in V} \text{indeg}(v) = \sum_{v \in V} \text{outdeg}(v)$$

Adjacency/weight matrix

$$A_G \in \mathbb{N}^{V \times V}$$

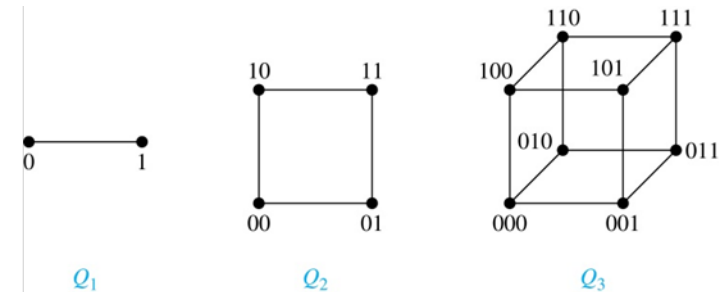
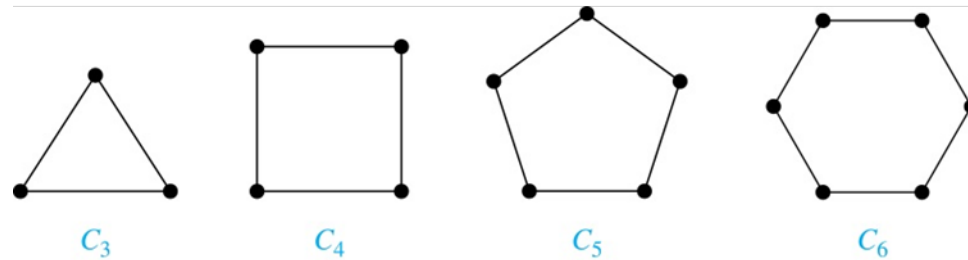
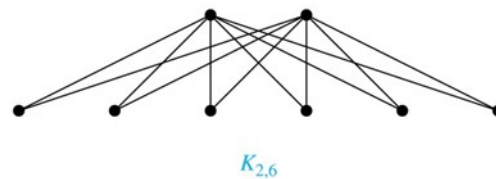
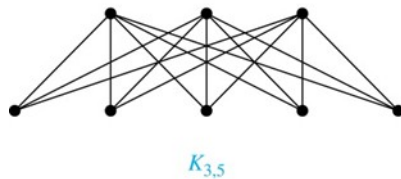
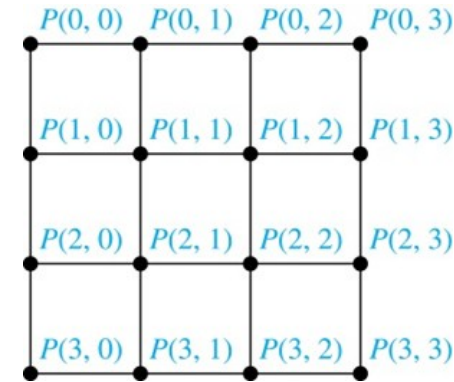
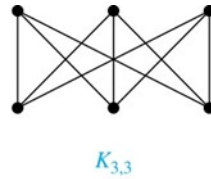
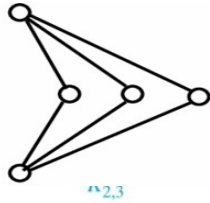
Powers of A_G



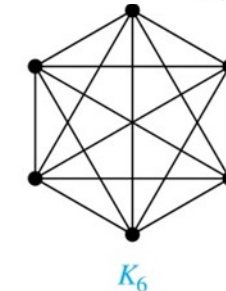
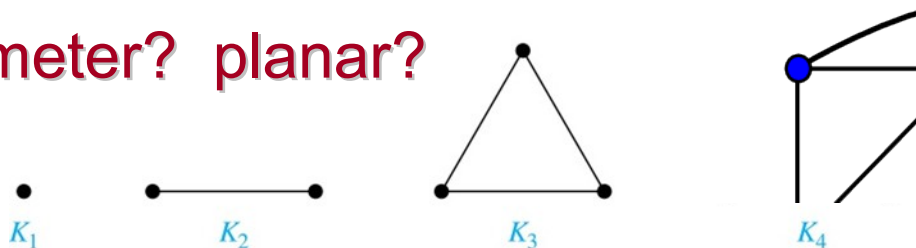
5. Graph Problems

graph examples

Specification: Graph $G=(V,E)$, $n=\#V$ vertices, $m=\#E$ edges



diameter? planar?



5. Graph Problems

Connectedness

Martin
Ziegler

Specification: Graph $G=(V,E)$, $n=\#V$ vertices, $m=\#E$ edges

Input: $A_G; s,t \in V$

Adjacency/weight matrix $A_G \in \mathbb{N}^{V \times V}$

Output: Is there a (directed) path from s to t in G ?

$A_{u,v} = \infty$
no edge

$A_{u,u} = 0$

DFS(v) // Is t reachable in G from v ?

If $v=t$ Return (**true**);

If v is marked *visited*

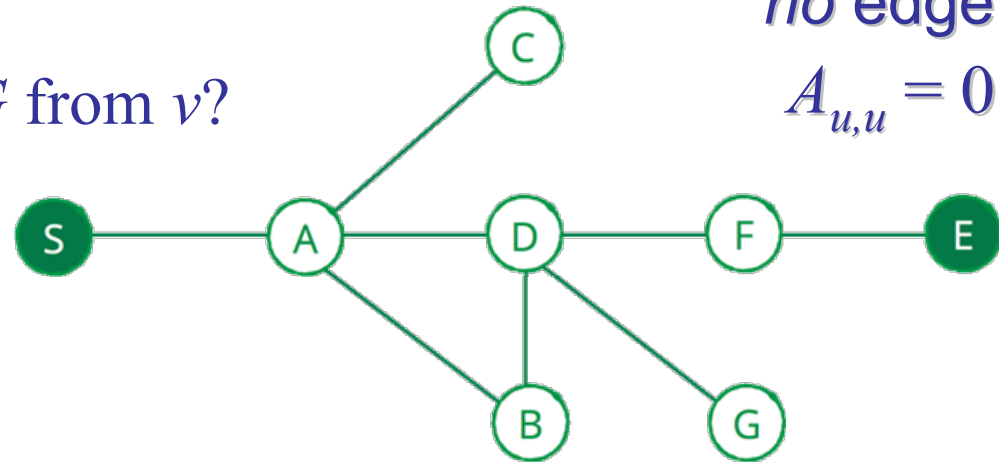
Return (**false**);

Mark v as *visited*;

For each neighbor u of v do

if **DFS**(u) Return (**true**);

Return (**false**);



Reachable(G,s,t)

For each vertex $v \in V$

Mark v as *unvisited*;

Return **DFS**(s)

5. Graph Problems

Shortest path(s)

Specification: Graph $G=(V,E)$, $n=\#V$ vertices, $m=\#E$ edges

Input: A_G $s,t \in V$ Adjacency/weight matrix $A_G \in \mathbb{N}^{V \times V}$

Output: weight $d(s,t)$ of lightest path from s to t .

Input: A_G $s \in V$ Adjacency/weight matrix $A_G \in \mathbb{N}^{V \times V}$

Output: For every $t \in V$, weight $d(s,t)$ of lightest path from s to t .

Input: A_G Adjacency/weight matrix $A_G \in \mathbb{N}^{V \times V}$

Output: For every $s,t \in V$, weight $d(s,t)$ of lightest path from s to t .

Remark: Shortest paths (on *non-negative* edge weights) are simple paths:

- W.l.o.g. consider only positive edge weights: otherwise merge vertices.
- In a shortest path $(s, v_1, v_2, \dots, v_k, \dots, v_l, \dots, t)$ from s to t , all segments (v_k, \dots, v_l) are shortest paths.

5. Graph Problems

Shortest path(s)

Specification: Graph $G=(V,E)$, $n=\#V$ vertices, $m=\#E$ edges

Input: $A_G; s \in V$ Adjacency/weight matrix $A_G \in \mathbb{N}^{V \times V}$

Output: For every $t \in V$, weight $d(s,t)$ of lightest path from s to t .

Dijkstra's Algorithm:

Mark all vertices *unvisited*.

set of *unvisited* vertices

Initialize $Q:=V$. tentativ distance from s

For each vertex v let $d_v:=\infty; d_s:=0$.

While $Q \neq \emptyset$ do

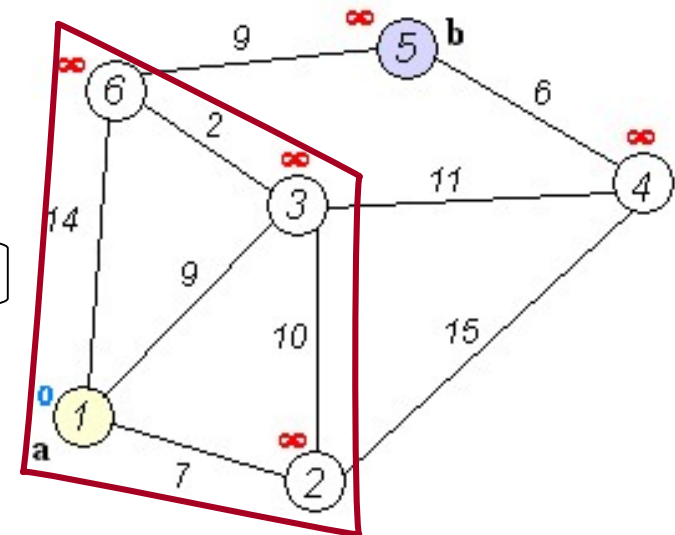
Correctness???

Extract from Q a vertex u with least d_u . Mark u as *visited*.

For each *unvisited* neighbor u of v do

If $d':=d_u+A_{uv} < d_v$ then decrease $d_v:=d'$.

$O(n \cdot \text{extractMin} + m \cdot \text{decreaseKey})$



5. Graph Problems

Shortest path(s)

Specification: Graph $G=(V,E)$, $n=\#V$ vertices, $m=\#E$ edges

Input: A_G Adjacency/weight matrix $A_G \in \mathbb{N}^{V \times V}$

Output: For every $t \in V$, weight $d(s,t)$ of *lightest* path from s to t .

Loop invariant $d_v \geq d(s,v)$. Suppose $M := \{ v : d_v > d(s,v) \} \neq \emptyset$.

Then $\delta := \min \{ d(s,v) : v \in M \}$ and $v \in M$ with $d(s,v) = \delta$ exist.

For (s, \dots, u, v) a *lightest* path to v , it holds $\delta > d(s,u) = d_u$.

Thus $d(s,v) = d(s,u) + A_{uv}$ and u gets extracted from Q before v . \hookleftarrow

For correctness, recall main loop: While $Q \neq \emptyset$ do

Extract from Q a vertex u with least d_u . Mark u as *visited*.

For each *unvisited* neighbor v of u do

If $d' := d_u + A_{uv} < d_v$ then decrease $d_v := d'$.

in increasing
order w.r.t. d

5. Graph Problems

All shortest paths

Specification: Graph $G=(V,E)$, $n=\#V$ vertices, $m=\#E$ edges

Input: A_G Adjacency/weight matrix $A_G \in \mathbb{N}^{V \times V}$

Output: For all $s,t \in V$, weight $d(s,t)$ of lightest path from s to t .

Floyd-Warshall Algorithm: runtime $O(n^3)$ $A_{u,v} = \infty$
no edge

For all pairs (u,v) of vertices, initialize $d_{u,v} := A_{u,v}$ $A_{u,u} = 0$

For each vertex $u \in V$

For each vertex $v \in V$

For each vertex $w \in V$

If $d_{v,w} > d_{v,u} + d_{u,w}$ then

$d_{v,w} := d_{v,u} + d_{u,w}$

Correctness

Dijkstra

(fixed $s \in V$):

$O(n \cdot \text{extractMin} + m \cdot \text{decreaseKey})$

Repeat for
each $s \in V$

5. Graph Problems *Min. Spanning Tree*

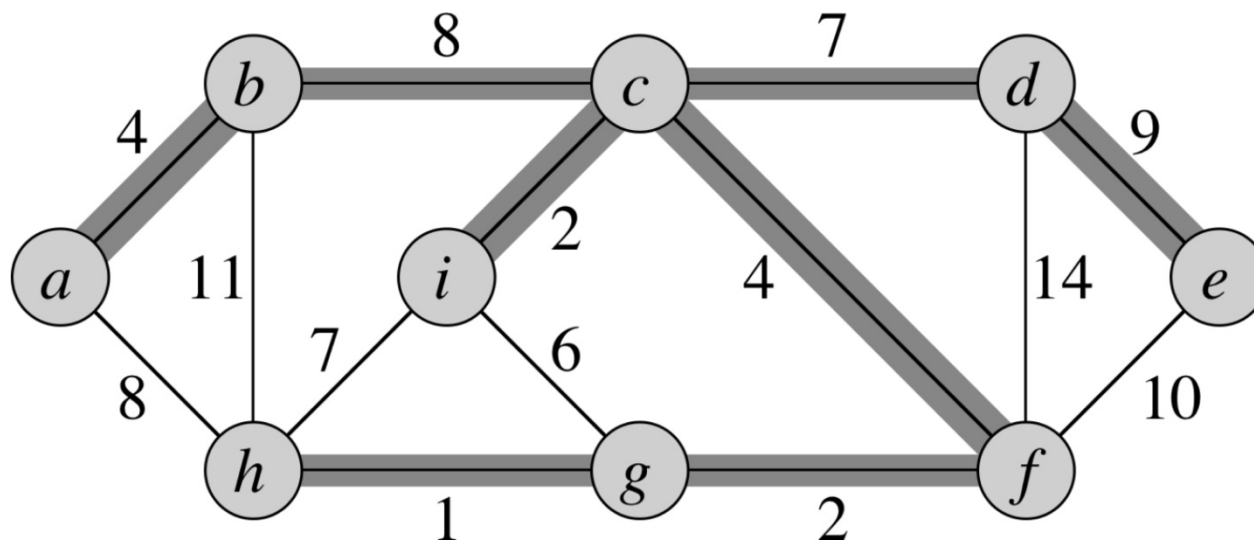
Specification: Graph $G=(V,E)$, $n=\#V$ vertices, $m=\#E$ edges

Input: A_G **Symmetric** adjacency/weight matrix $A_G \in \mathbb{N}^{V \times V}$

Output: $T \subseteq E$ spanning tree of least weight

s.t. (V,T) connected

$A_{u,v} = \infty$
no edge
 $A_{u,u} = 0$



5. Graph Problems

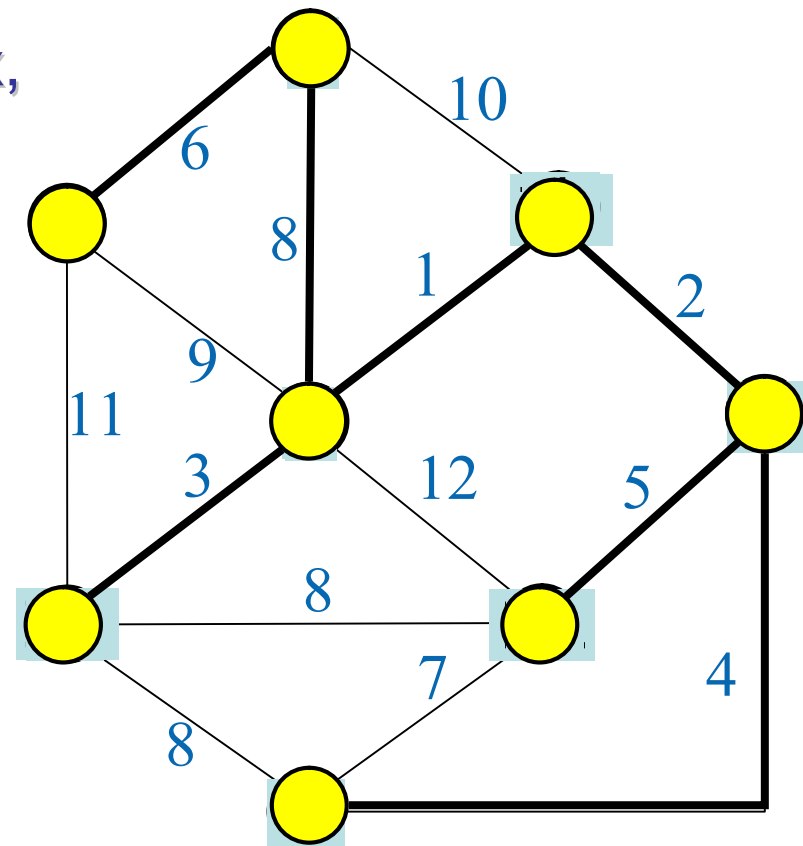
Prim's Algorithm

Specification: Graph $G=(V,E)$, $n=\#V$ vertices, $m=\#E$ edges

Input: A_G **Symmetric** adjacency/weight matrix $A_G \in \mathbb{N}^{V \times V}$

Output: $T \subseteq E$ spanning tree of least weight

1. Initialize a tree with a single vertex, chosen arbitrarily from the graph.
2. Grow the tree by one edge:
Of the edges that connect the tree to vertices not yet in the tree, **find the minimum-weight edge,** and transfer it to the tree.
3. Repeat step 2
(until all vertices are in the tree).



5. Graph Problems

Prim's Algorithm

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Zischler

Specification: Graph $G=(V,E)$, $n=\#V$ vertices, $m=\#E$ edges

Input: A_G **Symmetric** adjacency/weight matrix $A_G \in \mathbb{N}^{V \times V}$

Output: $T \subseteq E$ spanning tree of least weight

Initialize $F:=\emptyset$, $Q:=V$. Also:
 $d_v:=\infty$ and $e_v:=0$ for all $v \in V$.

While $Q \neq \emptyset$ do

Extract from Q
a vertex u with least d_u .

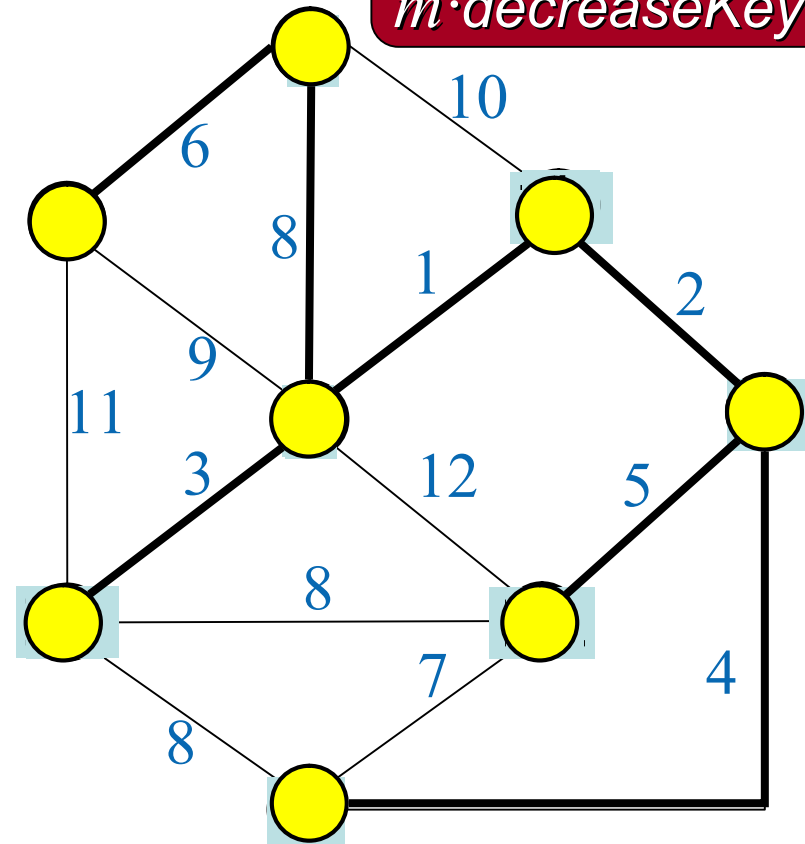
If $e_u \neq 0$, add edge (u, e_u) to F .

For each neighbor $v \in Q$ of u do

If $A_{uv} < d_v$ then

decrease $d_v := A_{uv}$; $e_v := u$;

$O(n \cdot \text{extractMin} + m \cdot \text{decreaseKey})$



5. Graph Problems

Kruskal Algorithm

Martin
Zisler

Specification: Graph $G=(V,E)$, $n=\#V$ vertices, $m=\#E$ edges

Input: A_G **Symmetric** adjacency/weight matrix $A_G \in \mathbb{N}^{V \times V}$

Output: $T \subseteq E$ spanning tree of least weight

Initialize the forest (=set of trees) with edges $F:=\{\}$, i.e., such that each vertex $v \in V$ is a separate tree.

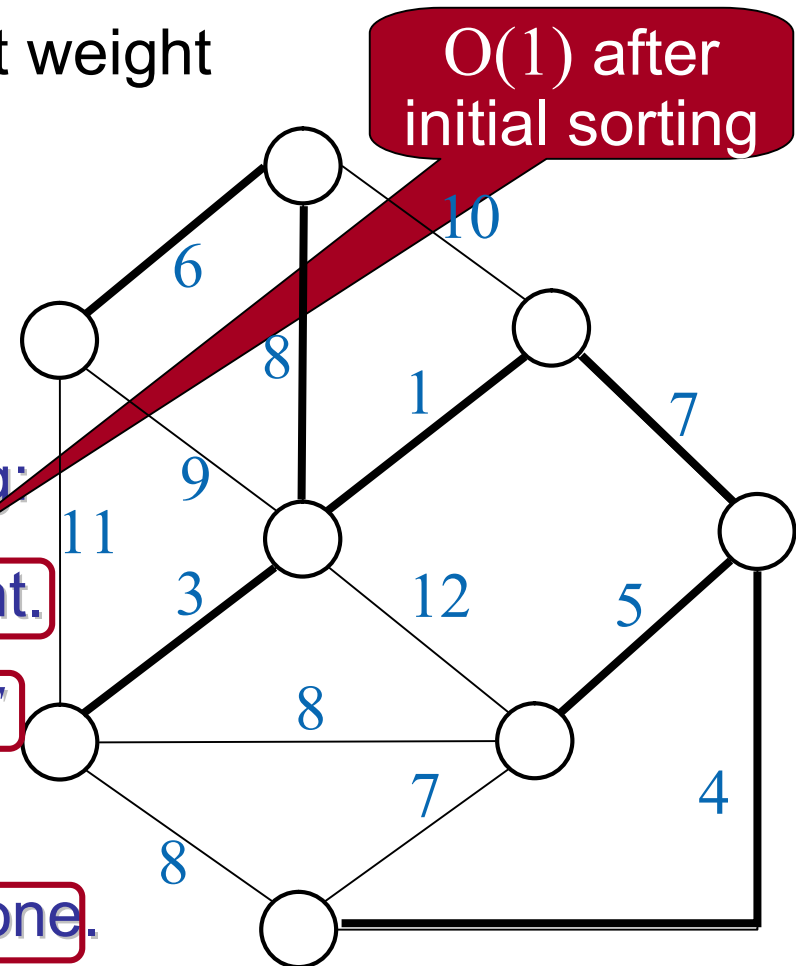
While $E \neq \{\}$ and F is not yet spanning:

Extract from E edge e of least weight.

If e connects two different trees of F

then add e to F , thus

combining two trees into a single one.



5. Graph Problems

Max Flow

Specification: Graph $G=(V,E)$, $n=\#V$ vertices, $m=\#E$ edges

Input: $s,t \in V$, A_G adjacency/weight matrix $A_G \in \mathbb{N}^{V \times V}$

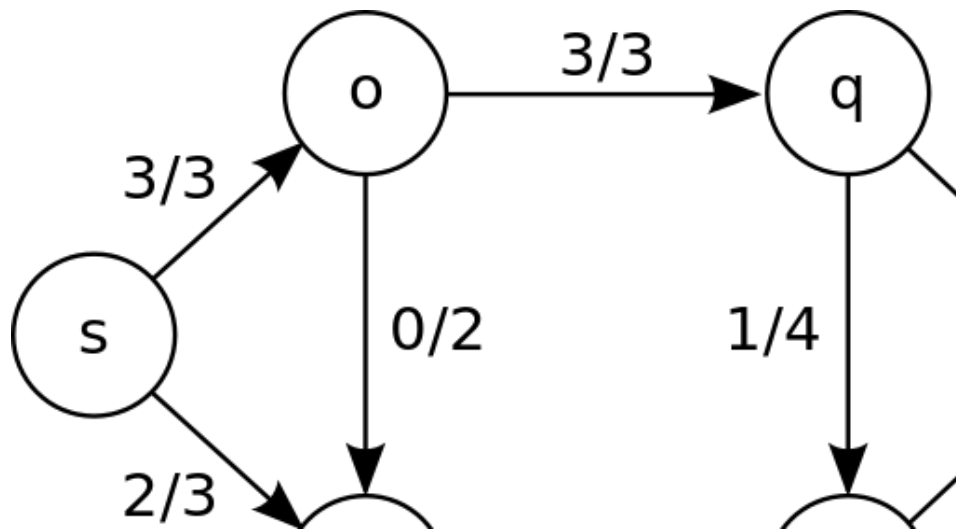
Output: $f: V^2 \rightarrow \mathbb{R}$ max. flow from s to t

Goal: maximize

$$\sum_{v:(s,v) \in E} f(s,v)$$

$$= \sum_{u:(u,t) \in E} f(u,t)$$

f flow (from s to t)



Lemma: There exists an *integral* maximal flow.

Def: A **flow** from s to t in G with weights $A \geq 0$ is a function

$f: V^2 \rightarrow \mathbb{R}$ such that $\forall v \in V \setminus \{s,t\}: \sum_{u:(u,v) \in E} f(u,v) = \sum_{w:(v,w) \in E} f(v,w)$

and $f(u,v) = -f(v,u)$. It is **admissible** if it holds $f(u,v) \leq A_{u,v}$

5. Graph Problems

Ford-Fulkerson

Specification: Graph $G=(V,E)$, $n=\#V$ vertices, $m=\#E$ edges

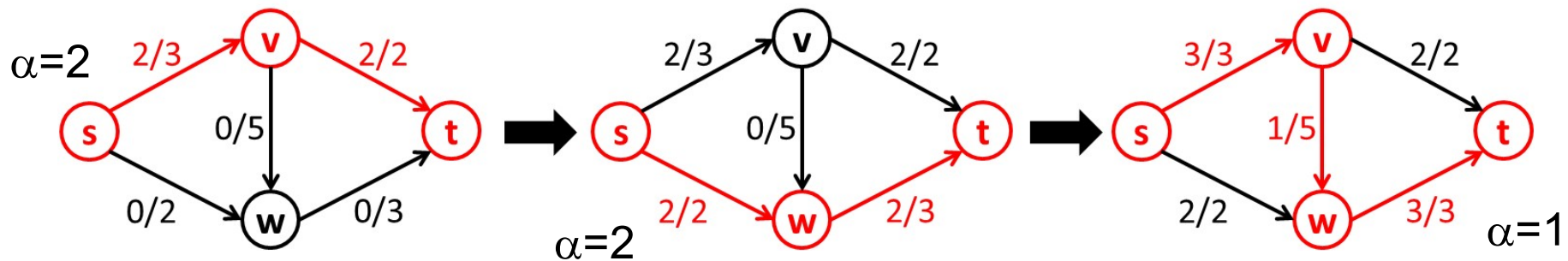
Input: $s,t \in V$, A_G adjacency/weight matrix $A_G \in \mathbb{N}^{V \times V}$

Output: $f: V^2 \rightarrow \mathbb{R}$ max. flow from s to t

Goal: maximize $|f| := \sum_{v:(s,v) \in E} f(s,v)$

The residual G_f of a graph G with flow f

has edges $E_f := \{ (u,v) : A_{u,v} > f(u,v) \vee f(v,u) > 0 \}$



Ford-Fulkerson: Initialize $f \equiv 0$. Correctness? Runtime $O(m \cdot |f|)$

While there exists some path $P = (s=u_1, \dots, u_K=t)$ from s to t in G_f

Let $\alpha := \min \{ A_{u_k, u_{k+1}} - f(u_k, u_{k+1}) : k=1 \dots K-1 \}$ and $f := f + \alpha \cdot P$.

5. Graph Problems

Edmonds-Karp

Specification: Graph $G=(V,E)$, $n=\#V$ vertices, $m=\#E$ edges

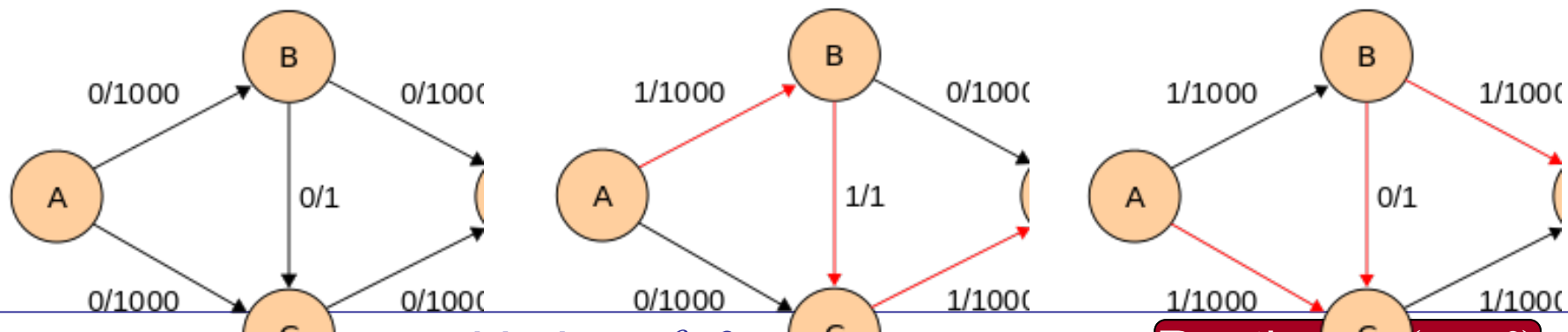
Input: $s,t \in V$, A_G adjacency/weight matrix $A_G \in \mathbb{N}^{V \times V}$

Output: $f: V^2 \rightarrow \mathbb{R}$ max. flow from s to t

Goal: maximize
 $|f| := \sum_{v:(s,v) \in E} f(s,v)$

The residual G_f of a graph G with flow f

has edges $E_f := \{ (u,v) : A_{u,v} > f(u,v) \vee f(v,u) > 0 \}$



Edmonds-Karp: Initialize $f \equiv 0$. shortest

Runtime $O(n \cdot m^2)$

While there exists some path $P = (s=u_1, \dots, u_K=t)$ from s to t in G_f

Let $\alpha := \min \{ A_{u_k, u_{k+1}} - f(u_k, u_{k+1}) : k=1 \dots K-1 \}$ and $f := f + \alpha \cdot P$.

5. Graph Problems

max. Bipartite Matching

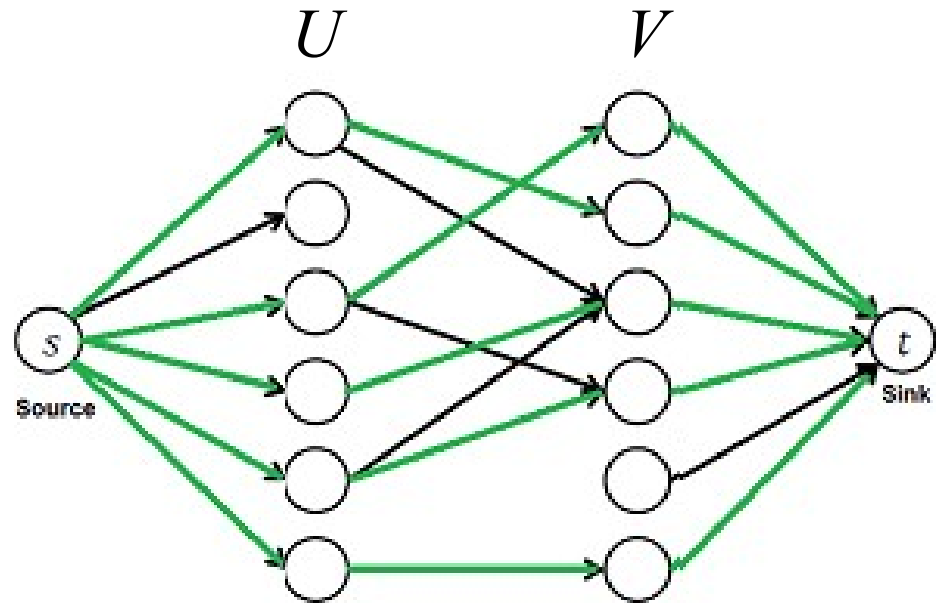
Specification: Bipartite graph $G=(U,V,E)$

Input: A_G

adjacency/weight matrix $A_G \in \mathbb{N}^{U \times V}$

Output: $F \subseteq E$ max. (weighted) matching

Reduction to *max. weighted flow*



Edmonds-Karp: Initialize $f \equiv 0$. **shortest**

Runtime $O(n \cdot m^2)$

While there exists some path $P = (s=u_1, \dots, u_K=t)$ from s to t in G_f

Let $\alpha := \min \{ A_{u_k, u_{k+1}} - f(u_k, u_{k+1}) : k=1 \dots K-1 \}$ and $f := f + \alpha \cdot P$.

Min Cut

5. Graph Problems

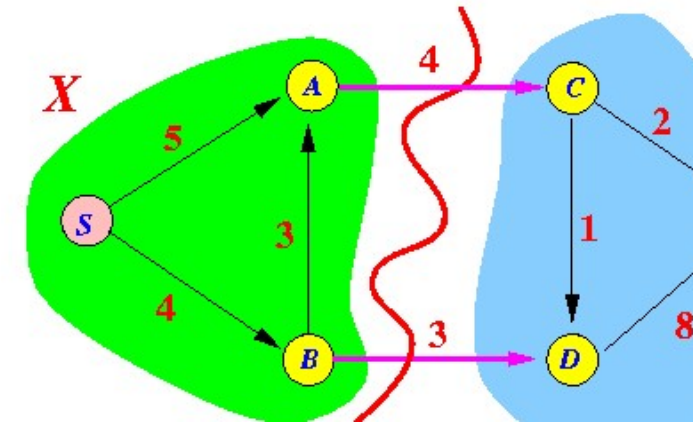
Specification: Graph $G=(V,E)$, $n=\#V$ vertices, $m=\#E$ edges

Input: $s,t \in V$, A_G adjacency/weight matrix $A_G \in \mathbb{N}^{V \times V}$

Output: $C \subseteq E$ min.cut between s,t

Def: A **cut** from s to t in G is a subset $C \subseteq V$ s.t. $s \in C$, $t \notin C$.

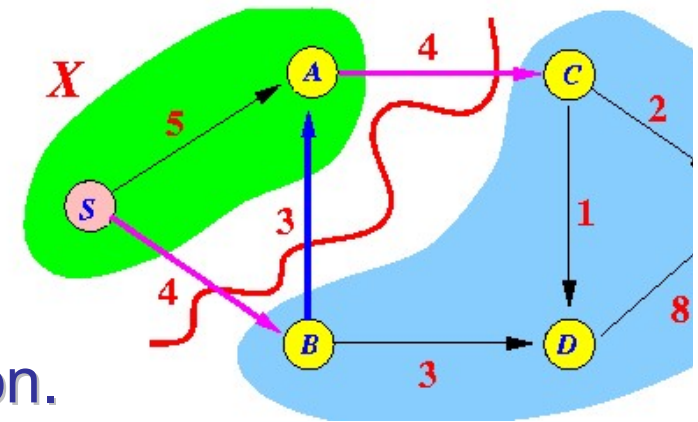
It has **capacity** $\lambda(C) = \sum_{\substack{(u,v) \in E \\ u \in C, v \notin C}} A_{u,v}$



Theorem: $\min_{C \text{ cut } (s,t)} \lambda(C) = \max_{f \text{ flow } (s,t)} |f|$

Proof "≥": For every C, f : $\lambda(C) \geq |f|$.

"≤": Consider $C \subseteq V$ all vertices reachable from s in G_f for max. f from Ford-Fulkerson.



Summary

5. Graph Problems

- Recap on Graphs: un/directed, weighted
- Shortest Paths: single-source, all-pairs
- Minimum Spanning Tree: Prim, Kruskal
- Maximum Flow: Ford-Fulkerson, Edmonds-Karp
- Maximum (weighted) Bipartite Matching
- Minimum Cut
- Planarity Testing, Maximum Matching → CS500